























































Strategy

AUTO	TELEOP	END GAME
15 sec	1 min 45 sec	30 sec

4.4.5 Point Values

Point values for tasks in INFINITE RECHARGE are detailed in Table 4-2.

Table 4-2: Point values

Award	Awarded for	AUTO	TELEOP	Qual.
INITIATION LINE	exit the infinite vertical volume created by the corresponding ALLIANCE'S INITIATION LINE any time before the end of AUTO (per ROBOT)	5	-	-
POWER CELLS	scored in BOTTOM PORT	2	1	-
	scored in OUTER PORT	4	2	-
	scored in INNER PORT	6	3	-
CONTROL PANEL	ROTATION CONTROL	-	15	-
	POSITION CONTROL		20	
ENDGAME Points	HANG (per ROBOT)	-	25	-
	PARK (per ROBOT)	-	5	-
	LEVEL with 1-3 ROBOTS HANGING (per ALLIANCE)		15	
SHIELD GENERATOR OPERATIONAL	earning at least sixty-five (65) ENDGAME points			1 Ranking Point
SHIELD GENERATOR ENERGIZED	Stage 3 ACTIVATED	-	-	1 Ranking Point
Tie	completing a MATCH with the same number of points as your opponent	-	-	1 Ranking Point
Win	completing a MATCH with more points than your opponent	-	-	2 Ranking Point

An ALLIANCE can earn up to four (4) Ranking Points (RP) per Qualification MATCH, as described in Table 4-2. There are no RP, or comparable point bonuses, in Playoff MATCHES.

Strategy Dictates Design



Ranking Points / Placement

Table 11-2 Qualification MATCH ranking criteria

Order Sort	Criteria
1 st	Ranking Score
2 nd	Cumulative AUTO points
3 rd	Cumulative ENDGAME points
4 th	Cumulative TELEOP POWER CELL and CONTROL PANEL points
5 th	Random sorting by the FMS

Ranking Points are earned during the match.

Table 11-3 Playoff MATCH Tiebreaker Criteria

Order Sort	Criteria
1 st	Cumulative FOUL and TECH FOUL points due to
and	
2 nd	Cumulative AUTO points
3 rd	Cumulative ENDGAME points
4 th	Cumulative TELEOP POWER CELL and CONTROL PANEL points
5 th	MATCH is replayed

Foul points are given to the other alliance and used as Tiebreaker.

Ranking Score is the average amount of RP's the team scores.

Autonomous & End Game Points are used as Tiebreakers.

Autonomous & End Game Points are used as Tiebreakers.



Chassis Shapes



Chassis Wheelbase

Chassis Wheel Base





Ratio of Track to Wheel base length: (2.0 to 2.5): 1

Turning Scrub

Chassis Drive Types

Chassis Wheel Configurations

Driven Wheel



Team 2228 CougarTech | 5

Chassis Drive Types

Arcade Drive

Tank Drive





Mecanum Drive





Chassis Drive Types

Mecanum Drive





Center of Turning / Pivot

2-wheel Drive 4-Wheel Drive Rotation

COT-Center Of Turning





Decreasing the distance between the front and rear set of wheels, results in better zero-radius turning in any direction with 4 wheel drive robot.

Skid Steering

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Center of Gravity / Mass

Newton's first law of motion states:

"An object at rest stays at rest and an object in motion stays in motion with the same speed and in the same direction unless acted upon by an unbalanced force." Objects tend to "keep on doing what they're doing."

For example: You are driving in a car at high speed and stop quickly. What happens to you?

Momentum:

When something is moving it has momentum. The heavier it is and the faster it is moving, the harder it is to stop. So, momentum is a kind of measurement of how hard it is to stop something in motion

Center of Gravity / Mass

Definition of CENTER OF GRAVITY

The point at which the entire weight of a body may be considered as concentrated so that if supported at this point the body would remain in equilibrium in any position(Merriam-Webster)

For example: The center of mass for a cube is the center of the cube.

Some rules for stability:

- It is more difficult to make an object with a low center of gravity topple than a structure with a high center of gravity.
- A structure with a wide base is generally more stable than a structure with narrow base.

Center of Gravity / Mass



High CoG – Robot will be more likely to tip over.

Low CoG – Robot will be more stable and will allow higher speeds and mobility.



Wheel Types







Intake Methods











Shooters







Shooters







Lifts, Linear Slides, & Ball Screws



Lifts, Linear Slides, & Ball Screws

Lifts, Linear Slides, & Ball Screws B_3 0 B_2

Pulleys, Sprockets & Gears

Pulleys, Sprockets & Gears

Gear Ratios

A **gear ratio** is the ratio of the number of rotations of a driver gear to the number of rotations of a driven gear.

gear ratio = rotations of a driver gear : rotations of a driven gear

Gear Ratios

What is the gear ratio? (gear ratio = rotations of a driver gear : rotations of a driven gear)

Ratio = output / input = 2/1

Gear Ratio = driver : driven = 2:1

Middle gear has no effect on the ratio of the gear train but does effect the rotation on the driven gear. Note that both gears are turning in the same direction now due to the idler gear.

Torque vs Speed

1:1 Gear ratio

Torque vs Speed

Motors & Servos

Sensors, Limits & Stops

SERVOCITY.

ROBOTICS

Tool Safety CHARLEN RIDGID

JAVA Programming WPI Visual Studio

OLYTECA

CAD & 3D Modeling

AUTODESK"

Scouting

Ready

Playoffs – Semi-Finals / Finals, 6 Teams of 3

Top 11 teams may be Alliance Team Captains.

What teams compliment your abilities?

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Community Outreach

Working in our community to promote STEM and FIRST Robotics.

- Homecoming Parade
- National Night Out
- Linden's Holiday Happening Events
- Farmer's Market
- Cub Scouts
- Elementary Schools FIRST Curriculum
- Wreaths Across America / Scholarships

Sustainability & Business Planning

- What do we do to make sure Linden Robotics will be here after we leave?
 - Elementary STEM activities
 - Middle School Program
 - Sponsorships & Local Partners
- We are a "business", a 501(3)(C) non-profit organization. We sell "advertising" to raise money to provide the programs.
- The cost to register a FRC team per season is \$5,000. Supplies, robot parts, uniforms, etc. are all extra expenses.

Sponsorships & Budget

- We have to have sponsors to keep the cost for each team member low.
- Sponsors can be local businesses, corporations, or organizations that promote educational opportunities.
- Parents offer opportunities to raise money for the programs. (ex. FORD, GM Dollars for Doers, etc.)
- We have to be mindful of how we spend the money we have available and to not be wasteful.

Robotics Board & Meetings

- There is a group of parents that are responsible to manage the assets of the Linden Robotics 501(3)(c).
- There are monthly Board Meetings where they decide what we do and how we spend the money.
- FRC team members must attend the meetings and provide a status for your season, and to request funds based on the team's needs.
- We may also need to attend School Board Meetings depending on current events or needs.

Coaches & Backgrounds

- Your Coaches and Mentors have varied backgrounds and abilities. We are here to help the team achieve your goals, not to build or design your robot.
- Coach Bonasse is a Senior Controls Engineering Supervisor with an Bachelor's of Science and Electrical Engineering degree(BSEE) from GMI.
- Coach Padilla is a Vehicle Performance Engineer.
- Coach Bucknam manages the outreach, sponsorships, and other background coordination for the team.
- Is there anyone that might want to help out?

Competitions & Judging

- First Qualifier Kettering, March 3rd 5th
- Second Qualifier Saline, March 25th 27th
- State Championship SVSU, April 13th 16th
- National Championship Houston, April 20th 23rd
- You have 2 chances to qualify for States.
- You will be judged several times in the pits. These interviews are what earn teams awards so it's imperative that everyone knows the robot, how the team functions, and can explain what we do and how we're active in our community.
- Our behavior on and off the field is critical.